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**Schaum's Outline of Theory and Problems of Basic Circuit Analysis** John O'Malley 1982 Confusing Textbooks? Missed Lectures? Not Enough Time?.. Fortunately for you, there's Schaum's Outlines. More than 40 million students have trusted Schaum's to help them succeed in the classroom and on exams. Schaum's is the key to faster learning and higher grades in every subject. Each Outline presents all the essential course information in an easy-to-follow, topic-by-topic format. You also get hundreds of examples, solved problems, and practice exercises to test your skills. . . This Schaum's Outline gives you. . Practice problems with full explanations that reinforce knowledge. Coverage of the most up-to-date developments in your course field. In-depth review of practices and applications. . . Fully compatible with your classroom text, Schaum's highlights all the important facts you need to know. Use Schaum's to shorten your study time-and get your best test scores!.. Schaum's Outlines-Problem Solved... .

**Electrical Circuit Theory and Technology** John Bird 2003-01-20 Electrical Circuit Theory and Technology is a fully comprehensive text for courses in electrical and electronic principles, circuit theory and electrical technology. The coverage takes students from the fundamentals of the subject, to the completion of a first year degree level course. Thus, this book is ideal for students studying engineering for the first time, and is also suitable for pre-degree vocational courses, especially where progression to higher levels of study is likely. John Bird's approach, based on 700 worked examples supported by over 1000 problems (including answers), is ideal for students of a wide range of abilities, and can be worked through at the student's own pace. Theory is kept to a minimum, placing a firm emphasis on problem-solving skills, and making this a thoroughly practical introduction to these core subjects in the electrical and electronic engineering curriculum. This revised edition includes new material on transients and laplace transforms, with the content carefully matched to typical undergraduate modules. Free Tutor Support Material including full worked solutions to the assessment papers featured in the book will be available at <http://textbooks.elsevier.com/>. Material is only available to lecturers who have adopted the text as an essential purchase. In order to obtain your password to access the material please follow the guidelines in the book.

**Basic Circuit Theory** Lawrence P. Huelsman 1984

**Linear Matrix Inequalities in System and Control Theory** Stephen Boyd 1994-01-01 In this book the authors reduce a wide variety of problems arising in system and control theory to a handful of convex and quasicnvex optimization problems that involve linear matrix inequalities. These optimization problems can be solved using recently developed numerical algorithms that not only are polynomial-time but also work very well in practice; the reduction therefore can be considered a solution to the original problems. This book opens up an important new research area in which convex optimization is combined with system and control theory, resulting in the solution of a large number of previously unsolved problems.

**Power Electronics** P. S. Bimbhra 2007

**A Mathematical Introduction to Robotic Manipulation** Richard M. Murray 2017-12-14 A Mathematical Introduction to Robotic Manipulation presents a mathematical formulation of the kinematics, dynamics, and control of robot manipulators. It uses an elegant set of mathematical tools that emphasizes the geometry of robot motion and allows a large class of robotic manipulation problems to be analyzed within a unified framework. The foundation of the book is a derivation of robot kinematics using the product of the exponentials formula. The authors explore the kinematics of open-chain manipulators and multifingered robot hands, present an analysis of the dynamics and control of robot systems, discuss the specification and control of internal forces and internal motions, and address the implications of the nonholonomic nature of rolling contact are addressed, as well. The wealth of information, numerous examples, and exercises make A Mathematical Introduction to Robotic Manipulation valuable as both a reference for robotics researchers and a text for students in advanced robotics courses.

**The Circuits and Filters Handbook, Third Edition (Five Volume Slipcase Set)** Wai-Kai Chen 2009-06-25 Standard-setting, groundbreaking, authoritative, comprehensive—these often overused words perfectly describe The Circuits and Filters Handbook, Third Edition. This standard-setting resource has documented the momentous changes that have occurred in the field of electrical engineering, providing the most comprehensive coverage available. More than 150 contributing experts offer in-depth insights and enlightened perspectives into standard practices and effective techniques that will make this set the first—and most likely the only—tool you select to help you with problem solving. In its third edition, this groundbreaking bestseller surveys accomplishments in the field, providing researchers and designers with the comprehensive detail they need to optimize research and design. All five volumes include valuable information on the emerging fields of circuits and filters, both analog and digital. Coverage includes key mathematical formulas, concepts, definitions, and derivatives that must be mastered to perform cutting-edge research and design. The handbook avoids extensively detailed theory and instead concentrates on professional applications, with numerous examples provided throughout. The set includes more than 2500 illustrations and hundreds of references. Available as a comprehensive five-volume set, each of the subject-specific volumes can also be purchased separately.

**Nonlinear Circuit Simulation and Modeling** José Carlos Pedro 2018-06-14 A practical, tutorial guide to the nonlinear methods and techniques needed to design real-world microwave circuits.

**Feedback Systems** Karl Johan Åström 2021-02-02 The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

**RF MEMS Circuit Design for Wireless Communications** Héctor J. de los Santos 2002 This is the first comprehensive book to address the design of RF MEMS-based circuits for use in high performance wireless systems. A groundbreaking research and reference tool, the book enables you to understand the realm of applications of RF MEMS technology; become knowledgeable of the wide variety and performance levels of RF MEMS devices; and partition the architecture of wireless systems to achieve greater levels of performance. This innovative resource also guides you through the design process of RF MEMS-based circuits, and establishes a practical knowledge base for the design of high-yield RF MEMS-based circuits. The book features exercises and detailed case studies on working RF MEMS circuits that help you decide what approaches best fit your design constraints. This unified treatment of RF MEMS-based circuit technology opens up a new world of solutions for meeting the unique challenges of low power/portable wireless products.

*Solution Manual to Engineering Mathematics* N. P. Bali 2010

**Optimal Control** Brian D. O. Anderson 2007-02-27 Numerous examples highlight this treatment of the use of linear quadratic Gaussian methods for control system design. It explores linear optimal control theory from an engineering

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viewpoint, with illustrations of practical applications. Key topics include loop-recovery techniques, frequency shaping, and controller reduction. Numerous examples and complete solutions. 1990 edition.

**Robust Control Design with MATLAB®** Da-Wei Gu 2006-03-30 Shows readers how to exploit the capabilities of the MATLAB® Robust Control and Control Systems Toolboxes to the fullest using practical robust control examples.

**Process Control** Jean-Pierre Corriou 2013-03-09 This reference book can be read at different levels, making it a powerful source of information. It presents most of the aspects of control that can help anyone to have a synthetic view of control theory and possible applications, especially concerning process engineering.

*A Linear Systems Primer* Panos J. Antsaklis 2007-12-03 Based on a streamlined presentation of the authors' successful work Linear Systems, this textbook provides an introduction to systems theory with an emphasis on control. Initial chapters present necessary mathematical background material for a fundamental understanding of the dynamical behavior of systems. Each chapter includes helpful chapter descriptions and guidelines for the reader, as well as summaries, notes, references, and exercises at the end. The emphasis throughout is on time-invariant systems, both continuous- and discrete-time.

**eIoT** Steffi O. Muhanjji 2019-02-20 This open access book explores the collision between the sustainable energy transition and the Internet of Things (IoT). In that regard, this book's arrival is timely. Not only is the Internet of Things for energy applications, herein called the energy Internet of Things (eIoT), rapidly developing but also the transition towards sustainable energy to abate global climate is very much at the forefront of public discourse. It is within the context of these two dynamic thrusts, digitization and global climate change, that the energy industry sees itself undergoing significant change in how it is operated and managed. This book recognizes that they impose five fundamental energy management change drivers: 1.) the growing demand for electricity, 2.) the emergence of renewable energy resources, 3.) the emergence of electrified transportation, 4.) the deregulation of electric power markets, 5.) and innovations in smart grid technology. Together, they challenge many of the assumptions upon which the electric grid was first built. The goal of this book is to provide a single integrated picture of how eIoT can come to transform our energy infrastructure. This book links the energy management change drivers mentioned above to the need for a technical energy management solution. It, then, describes how eIoT meets many of the criteria required for such a technical solution. In that regard, the book stresses the ability of eIoT to add sensing, decision-making, and actuation capabilities to millions or perhaps even billions of interacting "smart" devices. With such a large scale transformation composed of so many independent actions, the book also organizes the discussion into a single multi-layer energy management control loop structure. Consequently, much attention is given to not just network-enabled physical devices but also communication networks, distributed control & decision making, and finally technical architectures and standards. Having gone into the detail of these many simultaneously developing technologies, the book returns to how these technologies when integrated form new applications for transactive energy. In that regard, it highlights several eIoT-enabled energy management use cases that fundamentally change the relationship between end users, utilities, and grid operators. Consequently, the book discusses some of the emerging applications for utilities, industry, commerce, and residences. The book concludes that these eIoT applications will transform today's grid into one that is much more responsive, dynamic, adaptive and flexible. It also concludes that this transformation will bring about new challenges and opportunities for the cyber-physical-economic performance of the grid and the business models of its increasingly growing number of participants and stakeholders.

*Principles of Vibration* Benson H. Tongue 1996 Benson Tongue takes a refreshingly informal approach to the understanding and analysis of vibrations. He strikes the right balance between detail and accessibility, offering in-depth analysis and a friendly writing style. Beginning with classical subjects, e.g., single degree of freedom systems, the text moves into more modern material, emphasizing multiple degree of freedom systems. Numerous problems challenge students to think and analyze outcomes of various techniques employed. Additional modal analysis and linear algebra are incorporated to solve problems, utilizing but not requiring MATLAB. Another innovative feature of the text is a chapter devoted to "Seat of the Pants Engineering", which brings together some of the common approaches engineers use to get a quick answer or to verify an analysis. At the same time, he applies them to all the systems that have been discussed in earlier chapters.

Principles of Vibration is an ideal text for upper-level undergraduate and graduate students in mechanical, civil, and aeronautical engineering departments.

**Bayesian Inference of State Space Models** Kostas Triantafyllopoulos 2021-11-12 Bayesian Inference of State Space Models: Kalman Filtering and Beyond offers a comprehensive introduction to Bayesian estimation and forecasting for state space models. The celebrated Kalman filter, with its numerous extensions, takes centre stage in the book. Univariate and multivariate models, linear Gaussian, non-linear and non-Gaussian models are discussed with applications to signal processing, environmetrics, economics and systems engineering. Over the past years there has been a growing literature on Bayesian inference of state space models, focusing on multivariate models as well as on non-linear and non-Gaussian models. The availability of time series data in many fields of science and industry on the one hand, and the development of low-cost computational capabilities on the other, have resulted in a wealth of statistical methods aimed at parameter estimation and forecasting. This book brings together many of these methods, presenting an accessible and comprehensive introduction to state space models. A number of data sets from different disciplines are used to illustrate the methods and show how they are applied in practice. The R package BTSa, created for the book, includes many of the algorithms and examples presented. The book is essentially self-contained and includes a chapter summarising the prerequisites in undergraduate linear algebra, probability and statistics. An up-to-date and complete account of state space methods, illustrated by real-life data sets and R code, this textbook will appeal to a wide range of students and scientists, notably in the disciplines of statistics, systems engineering, signal processing, data science, finance and econometrics. With numerous exercises in each chapter, and prerequisite knowledge conveniently recalled, it is suitable for upper undergraduate and graduate courses.

**Applied Nonlinear Control** Jean-Jacques E. Slotine 1991 In this work, the authors present a global perspective on the methods available for analysis and design of non-linear control systems and detail specific applications. They provide a tutorial exposition of the major non-linear systems analysis techniques followed by a discussion of available non-linear design methods.

**Sensitivity Analysis: Matrix Methods in Demography and Ecology** Hal Caswell 2019-04-02 This open access book shows how to use sensitivity analysis in demography. It presents new methods for individuals, cohorts, and populations, with applications to humans, other animals, and plants. The analyses are based on matrix formulations of age-classified, stage-classified, and multistate population models. Methods are presented for linear and nonlinear, deterministic and stochastic, and time-invariant and time-varying cases. Readers will discover results on the sensitivity of statistics of longevity, life disparity, occupancy times, the net reproductive rate, and statistics of Markov chain models in demography. They will also see applications of sensitivity analysis to population growth rates, stable population structures, reproductive value, equilibria under immigration and nonlinearity, and population cycles. Individual stochasticity is a theme throughout, with a focus that goes beyond expected values to include variances in demographic outcomes. The calculations are easily and accurately implemented in matrix-oriented programming languages such as Matlab or R. Sensitivity analysis will help readers create models to predict the effect of future changes, to evaluate policy effects, and to identify possible evolutionary responses to the environment. Complete with many examples of the application, the book will be of interest to researchers and graduate students in human demography and population biology. The material will also appeal to those in mathematical biology and applied mathematics.

*Robot Manipulator Control* Frank L. Lewis 2003-12-12 Robot Manipulator Control offers a complete survey of control systems for serial-link robot arms and acknowledges how robotic device performance hinges upon a well-developed control system. Containing over 750 essential equations, this thoroughly up-to-date Second Edition, the book explicates theoretical and mathematical requisites for controls design and summarizes current techniques in computer simulation and implementation of controllers. It also addresses procedures and issues in computed-torque, robust, adaptive, neural network, and force control. New chapters relay practical information on commercial robot manipulators and devices and cutting-edge methods in neural network control.

*Advances in Telerobotics* Manuel Ferre 2007-08-10 A fascinating book that covers in detail all of the most recent advances in Telerobotics. A must-read for scientists, researchers and students in teleoperation, it describes everything from methods and experimental results to applications and developments. Its three sections cover human system interfaces, control, and applications.

*An Introduction to Hybrid Dynamical Systems* Arjan J. van der Schaft 2007-10-03 This book is about dynamical systems that are "hybrid" in the sense that they contain both continuous and discrete state variables. Recently there has been increased research interest in the study of the interaction between discrete and continuous dynamics. The present volume provides a first attempt in book form to bring together concepts and methods dealing with hybrid systems from various areas, and to look at these from a unified perspective. The authors have chosen a mode of exposition that is largely based on illustrative examples rather than on the abstract theorem-proof format because the systematic study of hybrid systems is still in its infancy. The examples are taken from many different application areas, ranging from power converters to communication protocols and from chaos to mathematical finance. Subjects covered include the following: definition of hybrid systems; description formats; existence and uniqueness of solutions; special subclasses (variable-structure systems, complementarity systems); reachability and verification; stability and stabilizability; control design methods. The book will be of interest to scientists from a wide range of disciplines including: computer science, control theory, dynamical system theory, systems modeling and simulation, and operations research.

**Bond Graph Modelling of Engineering Systems** Wolfgang Borutzky 2011-06-01 The author presents current work in bond graph methodology by providing a compilation of contributions from experts across the world that covers theoretical topics, applications in various areas as well as software for bond graph modeling. It addresses readers in academia and in industry concerned with the analysis of multidisciplinary engineering systems or control system design who are interested to see how latest developments in bond graph methodology with regard to theory and applications can serve their needs in their engineering fields. This presentation of advanced work in bond graph modeling presents the leading edge of research in this field. It is hoped that it stimulates new ideas with regard to further progress in theory and in applications.

*System Dynamics* Katsuhiko Ogata 2013-07-24 For junior-level courses in System Dynamics, offered in Mechanical Engineering and Aerospace Engineering departments. This text presents students with the basic theory and practice of system dynamics. It introduces the modeling of dynamic systems and response analysis of these systems, with an introduction to the analysis and design of control systems.

*Optimal Filtering* Brian D. O. Anderson 2012-05-23 Graduate-level text extends studies of signal processing, particularly regarding communication systems and digital filtering theory. Topics include filtering, linear systems, and estimation; discrete-time Kalman filter; time-invariant filters; more. 1979 edition.

**Introduction to PSpice Manual for Electric Circuits** James W. Nilsson 2001-12-01 The fourth edition of this work continues to provide a thorough perspective of the subject, communicated through a clear explanation of the concepts and techniques of electric circuits. This edition was developed with keen attention to the learning needs of students. It includes illustrations that have been redesigned for clarity, new problems and new worked examples. Margin notes in the text point out the option of integrating PSpice with the provided Introduction to PSpice; and an instructor's roadmap (for instructors only) serves to classify homework problems by approach. The author has also given greater attention to the importance of circuit memory in electrical engineering, and to the role of electronics in the electrical engineering curriculum.

**Stochastic Models, Estimation, and Control** Peter S. Maybeck 1982-08-25 This volume builds upon the foundations set in Volumes 1 and 2. Chapter 13 introduces the basic concepts of stochastic control and dynamic programming as the fundamental means of synthesizing optimal stochastic control laws.

*Transients in Electrical Systems: Analysis, Recognition, and Mitigation* J. C. Das 2010-05-06 Detect and Mitigate Transients in Electrical Systems This practical guide explains how to identify the origin of disturbances in electrical systems and analyze them for effective mitigation and control. Transients in Electrical Systems considers all transient frequencies, ranging from 0.1 Hz to 50 MHz, and discusses transmission line and cable modeling as well as frequency dependent behavior. Results of EMTP simulations, solved examples, and detailed equations are included in this comprehensive resource. Transients in Electrical Systems covers: Transients in lumped circuits Control systems Lightning strokes, shielding, and backflashovers Transients of shunt capacitor banks Switching transients and temporary overvoltages Current interruption in AC circuits Symmetrical and unsymmetrical short-circuit currents Transient behavior of synchronous generators, induction and synchronous motors, and transformers Power electronic equipment Flicker, bus, transfer, and torsional vibrations Insulation coordination Gas insulated substations Transients in low-voltage and grounding systems Surge arresters DC systems, short-circuits, distributions, and HVDC Smart grids and wind power generation

*Linear and Non Linear Circuits* Chua 2000-03-01

**Linear Controller Design** Stephen P. Boyd 1991

**Piecewise Linear Control Systems** Mikael K.-J. Johansson 2003-07-01 2. Piecewise Linear Modeling ..... 9 2. 1 Model Representation ..... 9 2. 2 Solution Concepts ..... 2 3 Uncertainty Models ..... 2 4 Modularity and Interconnections ..... 26 2. 5 Piecewise Linear Function Representations ..... 28 2. 6 Comments and References ..... 30 3. Structural Analysis ..... 32 3. 1 Equilibrium Points and the Steady State Characteristic . . . 32 3. 2 Constraint Verification and Invariance ..... 35 3. 3 Detecting Attractive Sliding Modes on Cell Boundaries 37 3. 4 Comments and References ..... 39 4. Lyapunov Stability ..... 41 4. 1 Exponential Stability ..... 41 4. 2 Quadratic Stability ..... 42 4. 3 Conservatism of Quadratic Stability ..... 46 4. 4 From Quadratic to Piecewise Quadratic ..... 48 4. 5 Interlude: Describing Partition Properties ..... 51 4. 6 Piecewise Quadratic Lyapunov Functions ..... 55 4. 7 Analysis of Piecewise Linear Differential

Inclusions . . . . . 61 4. 8 Analysis of Systems with Attractive Sliding Modes . . . . . 63 4. 9 Improving Computational Efficiency ..... 66 4. 10 Piecewise Linear Lyapunov Functions ..... 72 4. 11 A Unifying View ..... 77 4. 12 Comments and References ..... 82 5. Dissipativity Analysis ..... 85 5. 1 Dissipativity Analysis via Convex Optimization ..... 86 21 14 Contents Contents 5. 2 Computation of £2 induced Gain ..... 88 5. 3 Estimation of Transient Energy ..... 89 5. 4 Dissipative Systems with Quadratic Supply Rates ..... 91 5. 5 Comments and References ..... 95 Controller Design ..... 96 6. 1 Quadratic Stabilization of Piecewise Linear\* Systems . . . 97 6. 2 Controller Synthesis based on Piecewise Quadratics . . . 98 6. 3 Comments and References ..... 105 7. Selected Topics ..... 107 7. 1 Estimation of Regions of Attraction .....

**Networks of Dissipative Systems** Murat Arcak 2016-03-01 This book addresses a major problem for today's large-scale networked systems: certification of the required stability and performance properties using analytical and computational models. On the basis of illustrative case studies, it demonstrates the applicability of theoretical methods to biological networks, vehicle fleets, and Internet congestion control. Rather than tackle the network as a whole—an approach that severely limits the ability of existing methods to cope with large numbers of physical components—the book develops a compositional approach that derives network-level guarantees from key structural properties of the components and their interactions. The foundational tool in this approach is the established dissipativity theory, which is reviewed in the first chapter and supplemented with modern computational techniques. The book blends this theory with the authors' recent research efforts at a level that is accessible to graduate students and practising engineers familiar with only the most basic nonlinear systems concepts. Code associated with the numerical examples can be downloaded at extras.springer.com, allowing readers to reproduce the examples and become acquainted with the relevant software.

**Linear Theory of Hydrologic Systems** James Dooge 1973

**Handbook of Hybrid Systems Control** Jan Lunze 2009-10-15 Sets out core theory and reviews new methods and applications to show how hybrid systems can be modelled and understood.

**Linear System Theory and Design** Chi-Tsong Chen 1984 Uses simple and efficient methods to develop results and design procedures, thus creating a non-exhaustive approach to presenting the material; Enables the reader to employ the results to carry out design. Thus, most results are discussed with an eye toward numerical computation; All design procedures in the text can be carried out using any software package that includes singular-value decomposition, and the solution of linear algebraic equations and the Lyapunov equation; All examples are developed for numerical computation and are illustrated using MATLAB, the most widely available software package.

**Feedback Control Theory** John C. Doyle 2013-04-09 An excellent introduction to feedback control system design, this book offers a theoretical approach that captures the essential issues and can be applied to a wide range of practical problems. Its explorations of recent developments in the field emphasize the relationship of new procedures to classical control theory, with a focus on single input and output systems that keeps concepts accessible to students with limited backgrounds. The text is geared toward a single-semester senior course or a graduate-level class for students of electrical engineering. The opening chapters constitute a basic treatment of feedback design. Topics include a detailed formulation of the control design program, the fundamental issue of performance/stability robustness tradeoff, and the graphical design technique of loopshaping. Subsequent chapters extend the discussion of the loopshaping technique and connect it with notions of optimality. Concluding chapters examine controller design via optimization, offering a mathematical approach that is useful for multivariable systems.

**Basic Circuit Theory** Charles A. Desoer 1969

**Linear Systems** Panos J. Antsaklis 2006-11-24 "There are three words that characterize this work: thoroughness, completeness and clarity. The authors are congratulated for taking the time to write an excellent linear systems textbook!" —IEEE Transactions on Automatic Control Linear systems theory plays a broad and fundamental role in electrical, mechanical, chemical and aerospace engineering, communications, and signal processing. A thorough introduction to systems theory with emphasis on control is presented in this self-contained textbook, written for a challenging one-semester graduate course. A solutions manual is available to instructors upon adoption of the text. The book's flexible coverage and self-contained presentation also make it an excellent reference guide or self-study manual. For a treatment of linear systems that focuses primarily on the time-invariant case using streamlined presentation of the material with less formal and more intuitive proofs, please see the authors' companion book entitled A Linear Systems Primer.

**Basic Electric Circuit Theory** IsaaK D. Mayergoyz 2012-12-02 This is the only book on the market that has been conceived and deliberately written as a one-semester text on basic electric circuit theory. As such, this book employs a novel approach to the exposition of the material in which phasors and ac steady-state analysis are introduced at the beginning. This allows one to use phasors in the discussion of transients excited by ac sources, which makes the presentation of transients more comprehensive and meaningful. Furthermore, the machinery of phasors paves the road to the introduction of transfer functions, which are then used in the analysis of transients and the discussion of Bode plots and filters. Another salient feature of the text is the consolidation into one chapter of the material concerned with dependent sources and operational amplifiers. Dependent sources are introduced as linear models for transistors on the basis of small signal analysis. In the text, PSpice simulations are prominently featured to reinforce the basic material and understanding of circuit analysis. Key Features \* Designed as a comprehensive one-semester text in basic circuit theory \* Features early introduction of phasors and ac steady-state analysis \* Covers the application of phasors and ac steady-state analysis \* Consolidates the material on dependent sources and operational amplifiers \* Places emphasis on connections between circuit theory and other areas in electrical engineering \* Includes PSpice tutorials and examples \* Introduces the design of active filters \* Includes problems at the end of every chapter \* Priced well below similar books designed for year-long courses